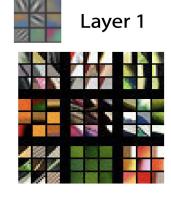
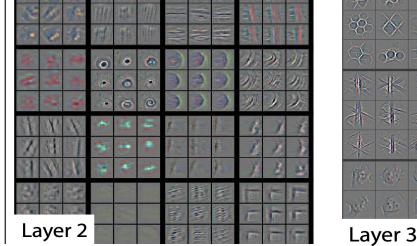
# A Theoretical Analysis on Feature Learning in Neural Networks: Emergence from Inputs and Advantage over Fixed Features

## Motivation

- Hidden Layers: good representations of the inputs for prediction
- **Neurons:** correspond to interesting patterns in the inputs







Visualization of neurons in a convnet

Figures from: Visualizing and Understanding Convolutional Networks, Zeiler and Fergus, ECCV'14.

#### **Questions**

- How features learned from inputs via gradient descent?
- Is learning features from inputs necessary for the superior performance?

#### Our results

- Propose a theoretical model of the data with input structure
- Prove network learning via gradient descent can succeed
- Prove fixed feature approaches fail
- Prove learning without input structure fails

## **Problem Setting**

**Dictionary Learning:** input = sparse combination of base patterns

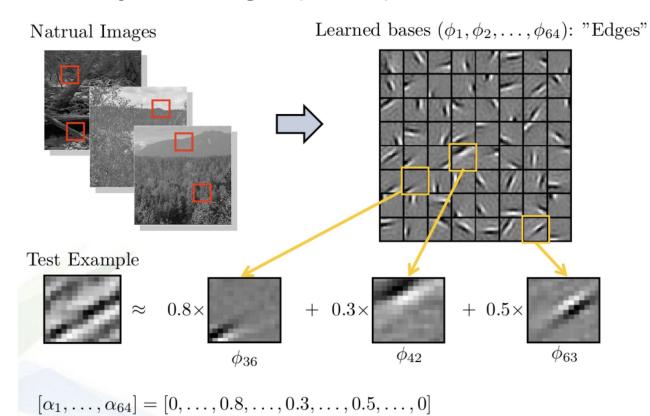


Figure from Brian Booth

- Input  $x = M\phi$ , with dictionary  $M \in \mathbb{R}^{d \times D}$ , and pattern indicator  $\phi \in \{0,1\}^D$
- Assume orthonormal M

Modeling the Labels: Relevant Pattern Counts

- 1. Sample  $\phi$  from distribution  $D_{\phi}$
- Generate input x using  $\phi$  and the dictionary M 2.
- 3. Generate label y using  $\phi$  and A, P

Assumptions on  $D_{\phi}$ 

- A. Balance classes:  $\Pr[y = +1] = \Pr[y = -1] = \frac{1}{2}$
- B. Relevant patterns: for any  $i \in A$ ,  $\gamma = \mathbf{E}[y\phi_i] \mathbf{E}[y]E[\phi_i] > 0$
- C. Irrelevant patterns: for any  $i \notin A$ ,  $\phi_i$  is i.i.d. with  $p_0 = \Pr[\phi_i = 1]$

Network: 2-Layer, Hinge-loss, L2-regularizer, Gaussian init, Gradient descent

- Train a network:  $g(x) = \sum_{i=1}^{2m} a_i \sigma(\langle w_i, x \rangle + b_i)$
- Activation: truncated ReLU  $\sigma(z) = \min(1, \max(0, z))$

## **Network Learning Result**

#### Theorem (informal)

k =

For any  $\epsilon, \delta \in (0,1)$ , if

$$\Omega\left(\log^2 \frac{Dm}{\delta \gamma}\right)$$
,  $p_0 = \Omega\left(\frac{k^2}{D}\right)$ ,  $m \ge \max\left\{D, \Omega\left(\frac{k^2}{\epsilon^1}\right)\right\}$ 

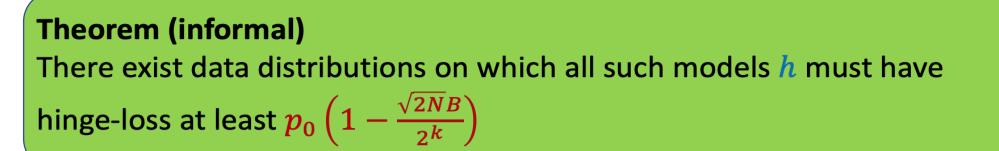
then with proper hyperparameters (e.g., step size), w.p. at least  $1 - \delta$ we can get a network with error at most  $\epsilon$ .

- With input structure, *poly*-size 2-layer neural networks can achieve small classification loss with high probability.
- 2. Success comes from feature learning:
  - First learns and improves the neuron weights s.t. there is a good classifier on the neurons
  - Then learns a good classifier

## Lower Bound for Fixed Feature Approach

#### • Fixed feature approach:

- Let  $\Psi(x) \in [-1,1]^N$  be any **data-independent** N-dim feature mapping
- Linear models  $h(x) = \langle \Psi(x), \theta \rangle$  with bounded weight  $||\theta||_2 \leq B$



There exist data distributions on which all *poly*-size fixed feature approaches cannot achieve as small loss.

## Lower Bound for Without Input Structure

- Without input structure: sample  $\phi$  uniformly from  $\{0,1\}^{D}$
- Statistical Query (SQ) algorithms:
  - Asks statistical queries  $(Q, \tau)$  about the data
  - Receives an estimation of  $\Pr[Q(x, y) \text{ is true}]$  within error  $\tau$

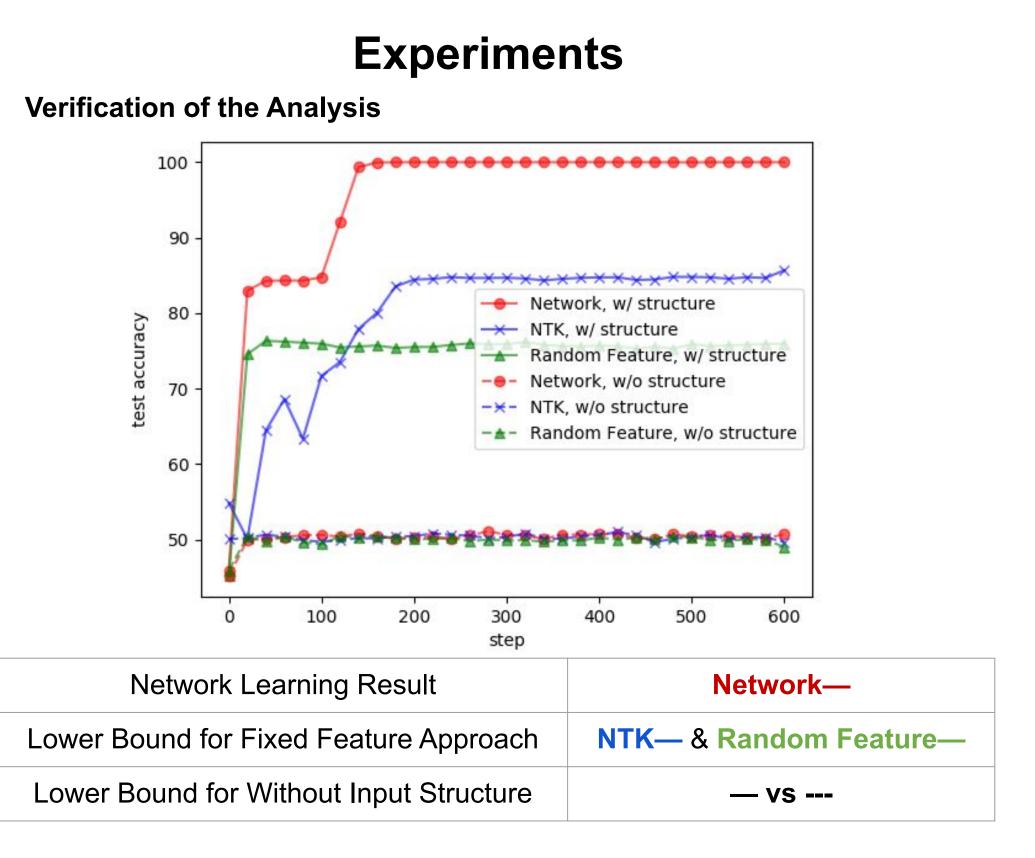
### Theorem (informal)

For any SQ algorithm that can learn without the input structure to classification error less than  $\frac{1}{2} - \frac{1}{(D)^3}$ , either the number of queries or  $\frac{1}{7}$  must be at least  $\frac{1}{2} {D \choose L}^{1/3}$ 

Without input structure, all poly algo in the Statistical Query model (including networks and fixed features above) cannot achieve as small loss.

## Zhenmei Shi\*, Junyi Wei\*, Yingyu Liang University of Wisconsin-Madison

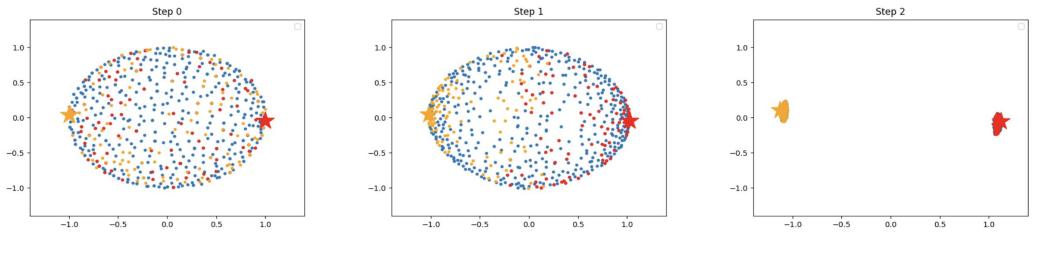




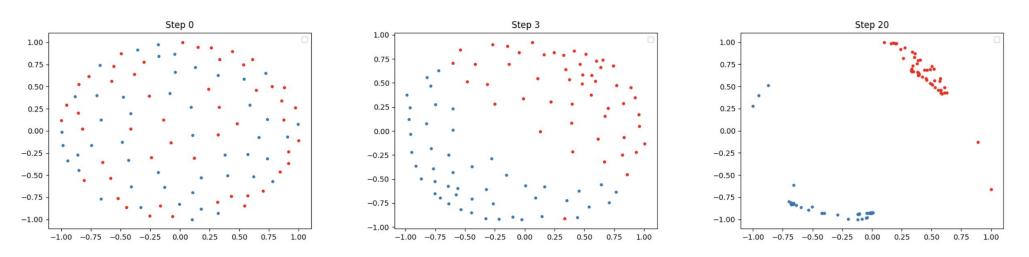
#### **Feature Learning on Synthetic Data**

#### • Visualization of the neuron weights (normalized to unit length)

• They clustered around  $\sum_{i \in A} M_i$  and  $-\sum_{i \in A} M_i$ 



#### Feature Learning on MNIST(0/1)



- The neurons gradually form two clusters around ground-truth weights
- Show the emergence of the features in the neural networks
- However, in fixed feature approaches, there is no feature learning

## Take Home Message

Input Structure -> Feature Learning Superior Performance